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http://www.kaysermotor.com

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CH-E. App. Co. LTD + Kayser Electric GmbH always adhering to the pursuit of professional application technology and international scientific management means, with the perfect professional knowledge and service concept to provide customers with high quality sports control products and intelligent management of new energy products, and by virtue of manufacturing advantages to further develop to provide customers with value-added services and flexible and reasonable business solutions. The integrated product providers and application technology providers of the program. From the industrial equipment manufacturing components to the office equipment parts, from the household appliance components to the precision instrument controls, Kayser Electrics seeks excellence and progress in a wide range of applications, bringing peace and convenience to the customers and creating value for the customers continuously.

Product application

Applications

- Industrial Equipment
- Textile
- Packaging
- Electronic Assembly
- Wood Working
- Semiconductor

Product features

Features

- · High torque in a small package: 40mm, 60mm, 80mm and 130mm diameters
- Power Range: 60 Watts to 4,000 Watts
- · Low cogging
- Windings for drive voltages from 240 VAC down to 24 VDC
- Optional Feedback Devices
 - · Incremental encoder
 - · Encoder with shared commutation signals
 - Absolute encoder
 - · Support multi brand
- · Low cost non sealed connectors, or Metal IP rated connectors
- Standard Brake Option
- Shaft Seals
- IP65 protection level (Capable to provide IP66 protective level)
- · All motors are CE, RoHS
- · Custom motors are available:
 - Shafts
 - Windings
 - Connectors
 - · Temperature Sensor
 - And More



COMPANY PROFILE

CH E. App. Co. LTD + Kayser Electric GmbH is a manufacturer in producing micro motors which has new management system and strong technology support. We mainly produce hybrid stepper motor, BLDC motor, DC brush motor, spindie motor and driver. The annual output is about 4 million units.

Our motors are widely used in cars, printers, ticket machines, caving machines, medical instruments, stage lightings, textile machines etc.

Kayser Electric is located in central China near Wuxi, with plant of 25000 square meters.

UNIT CONVERSION

Length

AB	mm	cm	m	inch	feet
mm	1	0.1	0.001	0.03937	0.003281
cm	10	1	0.01	0.3937	0.03281
m	1000	100	1	39.37	3.281
inch	25.4	2.54	0.0254	1	0.08333
feet	304.8	30.48	0.3048	12	1

Force

AB	g	kgf	oz	lb	Newton
g	1	0.001	0.03527	0.002205	0.0098
kgf	1000	1	35.27	2.205	9.807
oz	28.35	0.02835	1	0.0625	0.278
lb	453.6	0.4536	16	1	4.448
Newton	102	0.102	3.597	0.2248	1

Torque

A	Nm	Ncm	mNm	kgm*	kgcm*	gcm*	oz-in	lb-ft	lb-in
Nm	1	100	1000	0.102	10.2	10200	141.6	0.7376	8.851
Ncm	0.01	1	10	0.00102	0.102	102	1.416	0.007376	0.08851
mNm	0.001	0.1	1	0.000102	0.0102	10.2	0.1416	0.000738	0.008851
kgm*	9.807	980.7	9807	1	100	100000	1389	7.233	86.8
kgcm*	0.09807	9.807	98.07	0.01	1	1000	13.89	0.07233	0.868
gcm*	0.00009807	0.009807	0.09807	0.00001	0.001	1	0.01389	7.23E-05	0.000868
oz-in	0.007062	0.7062	7.062	0.0007201	0.07201	72.01	1	0.00521	0.0625
lb-ft	1.356	135.6	1356	0.1383	13.83	13830	192	1	12
lb-in	0.113	11.3	113	0.01152	1.152	1152	16	0.0833	1

Inertia

A B	kgm²	kgcm²	gcm²	oz-in²	oz-in-sec²	lb-in²	lb-in-sec ²	lb-ft²	"lb-ft-sec ² (slug ft ²)"
kgm²	1	10,000	10000000	54,700	142	3420	8.85	23.7	0.738
kgcm²	0.0001	1	1,000	5.47	0.0142	0.342	0.000885	0.00237	7.38E-05
gcm ²	0.0000001	0.001	1	0.00547	1.42E-05	0.000342	8.85E-07	2.37E-06	7.38E-08
oz-in²	0.00001829	0.1829	183	1	0.00259	0.0625	0.000162	0.000434	1.35E-05
oz-in-sec²	0.00706	70.62	70,600	386	1	24.1	0.0625	0.168	0.00521
lb-in ²	0.0002926	2.926	2,930	16	0.0414	1	0.00259	0.00694	0.000216
lb-in-sec ²	0.113	1,130	1130000	6,180	16	386	1	2.68	0.0833
lb-ft²	0.0421	421.4	421,000	2,300	5.97	144	0.373	1	0.0318
"lb-ft-sec ² (slug ft ²)"	1.36	13,600	13600000	74,100	192	4,630	12	32.2	1

MODEL NAMING RULES

KSX	60	05	Α	- 100	D	30	А	1	-001
Series	Seat No	Polar logarithm	Voltage	Power	Inertia	Speed	Encoder	Structure	Derivation of the same parameter

	Code	Meaning
60	40	40*40mm
	60	60*60mm
Seat No	80	80*80mm
	110	110*110mm
	130	130*130mm

KSX

_	_		
	Code	Meaning	
Dolar	04	4	
Polar logarithm	05	5	
	08	8	

	Code	Meaning
	Α	310VDC(220VAC)
	В	380VAC
	C	155VDC(110VAC)
	D	110VDC
	E	80VDC
Voltage	F	60VDC
	G	48VDC
	Н	36VDC
	K	24VDC

	8.4	44.5
	Code	Meaning
	10	100W
	20	200W
	40	400W
	75	750W
	95	950W
	100	1KW
	120	1.2KW
	135	1.35KW
	150	1.5KW
ower	180	1.8KW
	200	2KW
	240	2.4KW
	300	3KW
	330	3.3KW
	400	4KW
	420	4.2KW
	500	5KW
	510	5.1KW
	Code	Meaning

	Code	Meaning
S D Inertia E H	Small inertia	
	Medium inertia	
	Large inertia	
	Increase of inertia	
_		
	Code	Meaning

	Code	Meaning
	6	600rpm
	10	1000rpm
	15	1500rpm
Spred	20	2000rpm
	30	3000rpm
		*100

	Code	Meaning
	A	Tamagawa single ring absolute value 17bit (When the incremental 17bit is used)
	В	Incremental 2500ppr (Optical encoder)
	L	Tamagawa single ring absolute value 17bit
Encoder	М	Rotary transformer
	Υ	Yuheng multi ring absolute 17bit
ı		Not encoders
	Р	Tamagawa single ring absolute value 23bit
	N	Nikon multi ring absolute value

	Code	Meaning
	1	Key shaft, Oil seal, No brake
	2	Key shaft. Oil seal. Brake
	3	Key shaft. NO oil seal. No brake
	4	Key shaft. NO oil seal, brake
Sincture	5	Optic axis, NO oil seal, No brake
	6	Optic axis. Oil seal. brake
	7	Optic axis. NO oil seal. No brake
	8	Optic axist、NO oil seal、brake





40 SERIES SERVO MOTOR





General Specifications

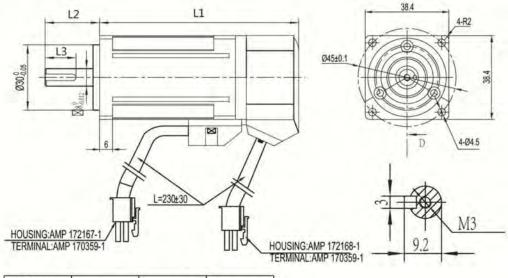
The operating	-20 C~+50 C
Insulation class	F
Safe class	IP65

Model				KSX40			
Rated power(W)				100			
Rated voltage(V)				220			
Rated current(A)				1.1			
Rated speed(rpm)				3000			
Rated torque(N.m)				0.32			
Max torque(N.m)				0.96			
Voltage constant(V/1000rmp)				19			
Torque coefficient(N.m/A)				0.265			
Rotor inertia(Kg.mf)				0.045*10*			
Line-line resistance(Ω)				11			
Line-line inductance(mH)				8.5			
Mechanical time-constant(Ms)				2			
Weight				0.5kg			
	Winding lead wire	U(red)		V(white)	W(black)	PE()	vellow/green
Motor winding plug	Plug serial number	1		2	3		4
Plug winding plug		1	2	3	4	5	6
Signal lead wire		NC	SD+	SD-	Vcc	GND	Shild

^{*}The above products are only representative products, and the derived products can be made according to customer requirements.

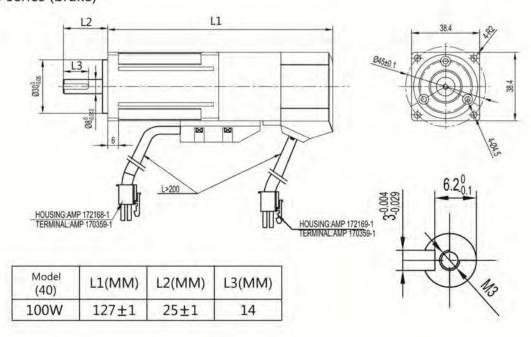
KSX40 installation dimension

40 series (No brake)



Model (40)	L1(MM)	L2(MM)	L3(MM)
100W	91.5±1	25±1	14

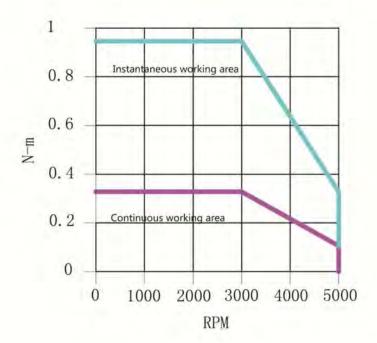
40 series (brake)





KSX40

T-N Curve 40 SERIES







60 SERIES SERVO MOTOR





General Specifications

The operating	-20 C~+50 C
Insulation class	F
Safe class	IP65

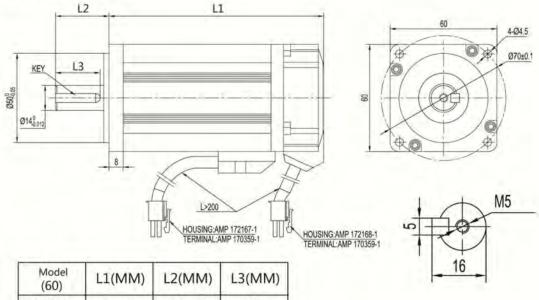
Model	KSX60			KSX60		KSX6	50
Rated power(W)	100			200		400	
Rated voltage(V)	220			220		220	
Rated current(A)	1.1			1.6		2.6	
Rated speed(rpm)	3000			3000		3000	
Rated torque(N.m)	0.32			0.64		1.3	
Max torque(N.m)	0.96			1.92		3,9	
Voltage constant(V/1000rmp)	19			37		32	
Torque coefficient(N.m/A)	0.265			0.45		0.48	
Rotor inertia(Kg.m²)	0.22*10*			0.45*10*	0.67*10*		
Line-line resistance(Ω)	11			8.8		3.7	
Line-line inductance(mH)	8,5			24		12	
Mechanical time-constant(Ms)	2			2		2	
Weight	0.5kg			0.8kg		1kg	
	Winding lead wire	U(red)		V(white)	W(black)	PE()	vellow/green
Motor winding plug	Plug serial number	.1		2	3		4
Plug winding plug		1	2	3	4	5	6
Signal lead wire		NC	SD+	SD-	Vcc	GND	Shild

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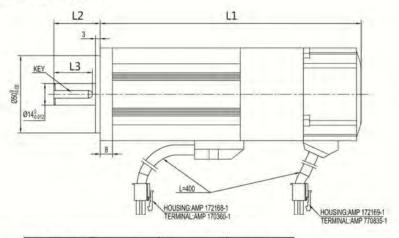
installation dimension KSX60

60 series (No brake)

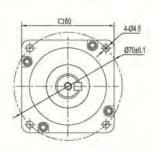


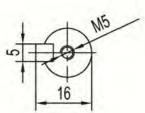
Model (60)	L1(MM)	L2(MM)	L3(MM)
100W	71±1	30±1	25
200W	116±1	30±1	25
400W	121±1	30±1	25

60 series (brake)

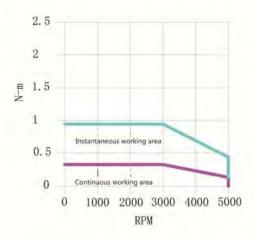


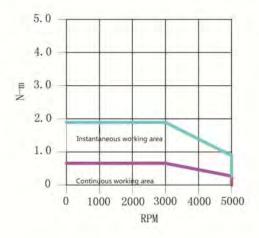
Model (60)	L1(MM)	L2(MM)	L3(MM)
100W	130±1	30±1	25
200W	150±1	30±1	25
400W	170±1	30±1	25

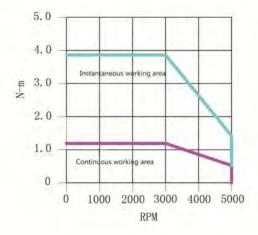




T-N Curve 40 SERIES











80 SERIES SERVO MOTOR





General Specifications

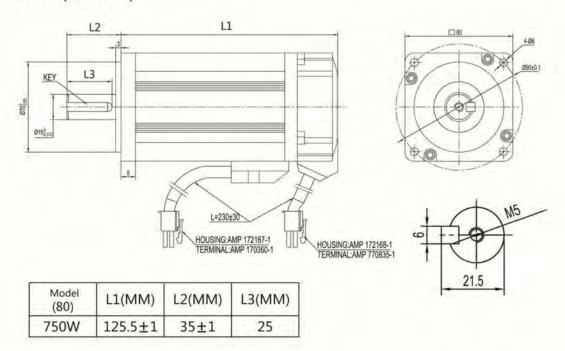
The operating	-20 C~+50 C
Insulation class	F
Safe class	IP65

Model				KSX80			
Rated power(W)				750			
Rated voltage(V)				220			
Rated current(A)				4.0			
Rated speed(rpm)				3000			
Rated torque(N.m)				2.4			
Max torque(N.m)				7.2			
Voltage constant(V/1000rmp)				39			
Torque coefficient(N.m/A)				0.6			
Rotor inertia(Kg.m²)				1.51*10			
Line-line resistance(Ω)				1.5			
Line-line inductance(mH)				11			
Weight				3.3kg			
Mechanical time-constant(Ms)				2			
	Winding lead wire	U(red)		V(white)	W(black)	PE()	vellow/green)
Motor winding plug	Plug serial number	1		2	3		4
Plug winding plug		1	2	3	4	5	6
Signal lead wire		NC	SD+	SD-	Vcc	GND	Shild

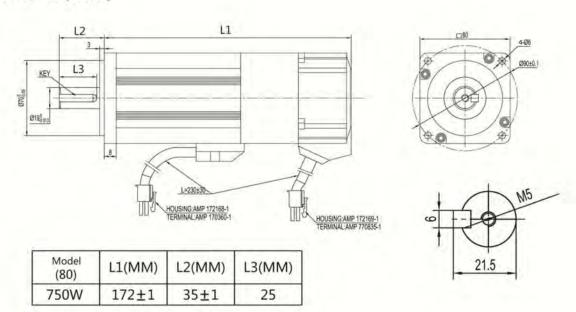
^{*}The above products are only representative products, and the derived products can be made according to customer requirements.



80 series (No brake)

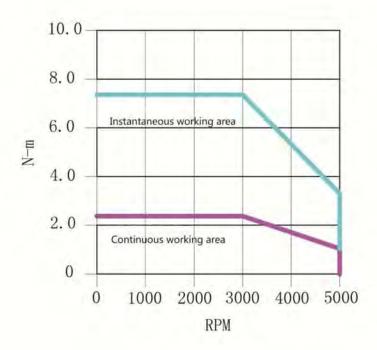


80 series (brake)





T-N Curve 80 SERIES





KSX130

130 SERIES SERVO MOTOR





General Specifications

The operating	-20 C~+50 C	
Insulation class	F	
Safe class	IP65	

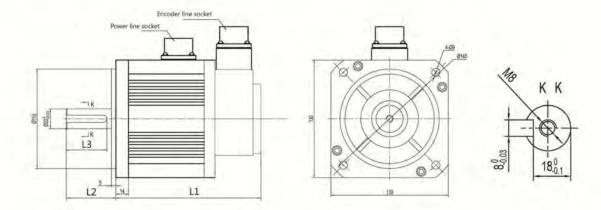
Model	KSX	130		KSX13	0		KSX130	
Rated power(W)	100	0		1500			2000	
Rated voltage(V)	220)		220			220	
Rated current(A)	5.8	1.		8.8			10	
Rated speed(rpm)	200	0		2000			2000	
Rated torque(N.m)	4.7			7.2			10	
Max torque(N.m)	14.	1		21.6			30	
Voltage constant(V/1000mp)	55			62			62	
Torque coefficient(N.m/A)	0.8	5		0.85			1	
Rotor inertia(Kg.m [†])	4.5*1	01		6.7*10	,		8.7*10*	
Line-line resistance(Ω)	1.2	2		0.8			0.6	
Line-line inductance(mH)	12			8.4			8	
Mechanical time-constant(Ms)	2			2			2	
Weight	7,5k	g		9.5kg			11.5kg	
	Winding lead wire	U(red)		V(white)	W(black)		PE(yellow/gr	een)
Motor winding plug	Plug serial number	А		В	С		PE	
Plug winding plug		Н	G	T	S	К	L	J
Signal lead wire		+5V	GND	BAT+	BAT-	SD+	SD-	Shi

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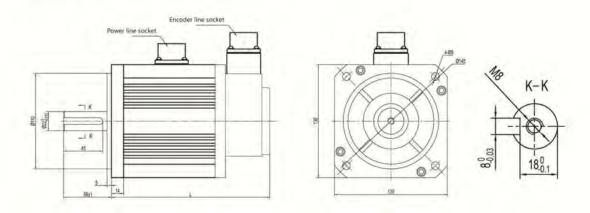
installation dimension KSX130

130 series (No brake)



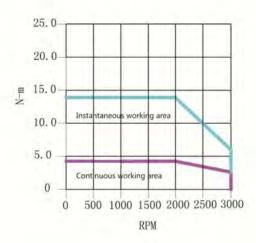
Model (130)	L1(MM)	L2(MM)	L3(MM)
1000W	143.5±1	55±1	45
1500W	159±1	55±1	45
2000W	171±1	55±1	45

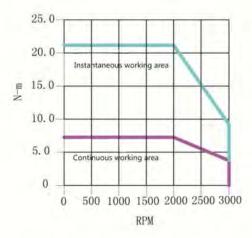
130 series (brake)

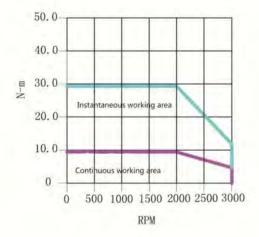


Model (130)	L1(MM)	L2(MM)	L3(MM)
1000W	182.5±1	55±1	45
1500W	196±1	55±1	45
2000W	210±1	55±1	45

T-N Curve 130 SERIES











40 SERIES LOW VOLTAGE SERVO MOTOR





General Specifications

The operating	-20 ℃~+50 ℂ	
Insulation class	F	
Safe class	IP65	

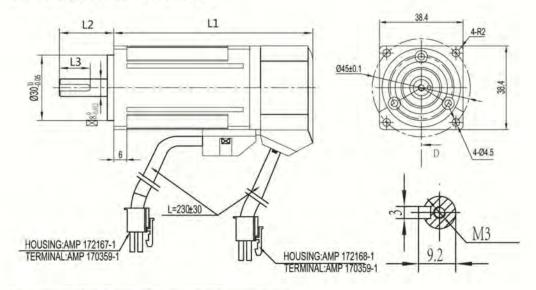
Model					KSX60				
Rated power(W)					100				
Rated voltage(V)					24				
Rated current(A)					5.6				
Rated speed(rpm)					3000				
Rated torque(N.m)					0.32				
Max torque(N.m)					0.9				
Voltage constant(V/1000rm)	p)				6				
Torque coefficient(N.m/A)					0.057				
Rotor inertia(Kg.mf)				(0.045*10*				
Line-line resistance(Ω)					0.6				
Line-line inductance(mH)	1 -				0.86				
Mechanical time-constant(M	ls)				1.08				
Weight					0.5kg				
	Winding lead wire	black	blue	red	brown/t	olack	brown	blue/black	gray
Motor winding plug	Plug serial number	1	3	4	5		6	7	9
Plug winding plug	1	2	3	4	5	6	7.	8	9
Signal lead wire	OV	1.	SD+	+5V	BAT-	BAT+	SD-	1	GND

^{*}The above products are only representative products, and the derived products can be made according to customer requirements.

installation dimension

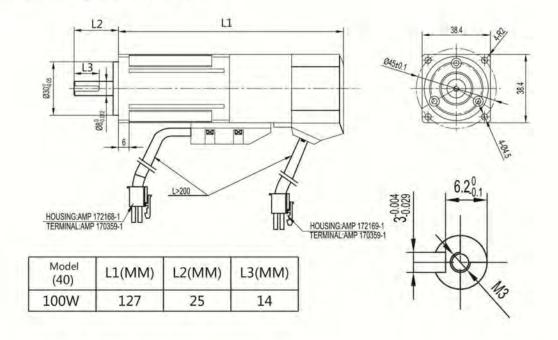
40 low voltage SERIES

40 low voltage series (No brake)



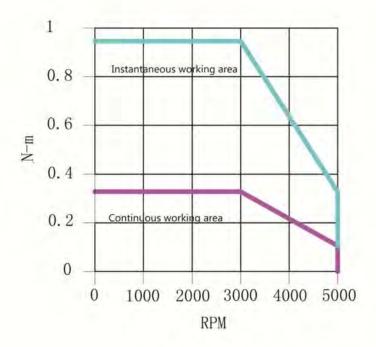
Model (40)	L1(MM)	L2(MM)	L3(MM)
100W	97	25	14

40 low voltage series (brake)



KSX40

T-N Curve







60 SERIES LOW VOLTAGE SERVO MOTOR





General Specifications

The operating	-20 C~+50 C
Insulation class	F
Safe class	IP65

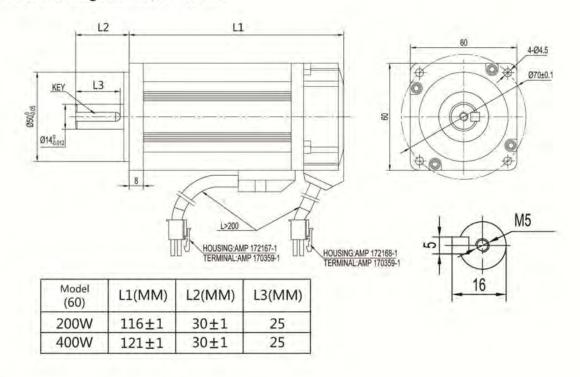
Model					KSX6	0	_				KSX	60			
Rated power(W)					200						400)			
Rated voltage(V)					36						48				
Rated current(A)					9						12				
Rated speed(rpm)					3000						300	0			
Rated torque(N,m)					0.64						1.2	7			
Max torque(N.m)					1.92						3.8	1			
Voltage constant(V/1000rmp)				******						****	-			
Torque coefficient(N.m/A)											****	+			
Rotor inertia(Kg.m²)				0	.32*10	0*					0.45*	101			
Line-line resistance(Ω)					0.25						0.29	9			
Line-line inductance(mH)					0.5						0.6	5			
Mechanical time-constant(M	s)				1.3						1.3				
Weight					1.5kg						1.9k	g			
Anna and an and a	Winding le	ad wire	bled	red oran	ge blue I	brawn yella	w green	gray on	ange/white	blue/white	brown/w	hile yello	w/while gr	rean/while	gra
Motor winding plug	Plug serial	number	1	2 3	4	5 6	7	8	10	111	12		13	14	
Plug winding plug	1	2	3	4	5	6	7	8	9	10	11	12	13	14	
Signal lead wire	GND	+5V	W+	V+	U+	Z+	B+	A+	TM	W-	V-	U-	Z-	B-	

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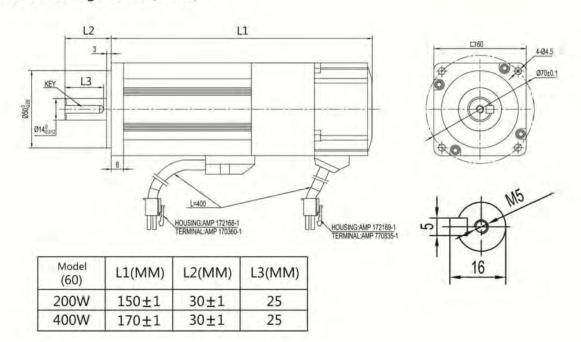


installation dimension

60 low voltage series(NO brake)



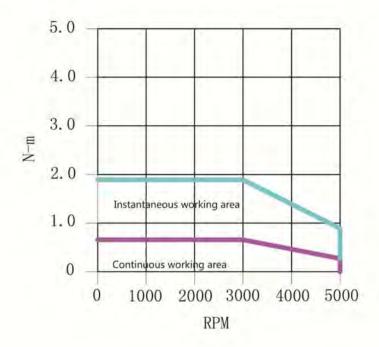
60 low voltage series (brake)

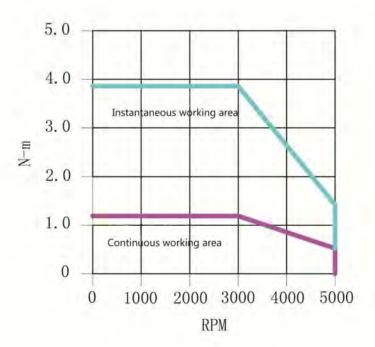


KSX60

T-N Curve











80 SERIES LOW VOLTAGE SERVO MOTOR





General Specifications

The operating	-20 C ~+50 C
Insulation class	F
Safe class	IP65

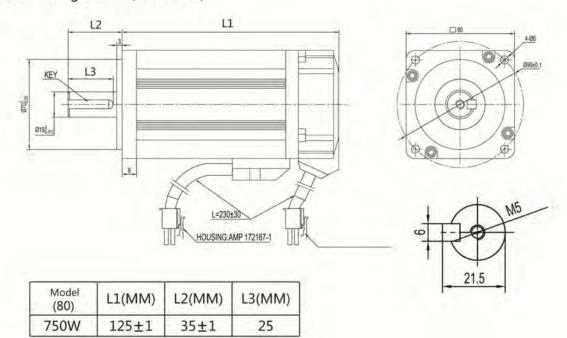
Model								KSX8	0						
Rated power(W)								750							
Rated voltage(V)								48							
Rated current(A)								20							
Rated speed(rpm)				3000											
Rated torque(N.m)								2.38							
Max torque(N.m)								7.2							
Voltage constant(V/1000rm	np)							8							
Torque coefficient(N.m/A)							0.13	2						
Rotor inertia(Kg.m²)								1.51*1	10*						
Line-line resistance(Ω)								0.15							
Line-line inductance(mH)								0.5							
Weight								0.5kg	9						
Mechanical time-constant(N	Ms)							1.1							
	Winding le	ad wire	black	ted aran	ge blue	brown ye	low green	gray or	ange/white	blue/white	brown/w	hite yello	w/white g	reen/white	gray/w
Motor winding plug	Plug serial	number	t	2 3	4	5	6 7	8	10	11	12		13	14	18
Plug winding plug	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Signal lead wire	GND	+5V	W+	V+	U+	Z+	B+	A+	TM	W-	V-	U-	Z-	B-	A

^{*}The above products are only representative products, and the derived products can be made according to customer requirements.

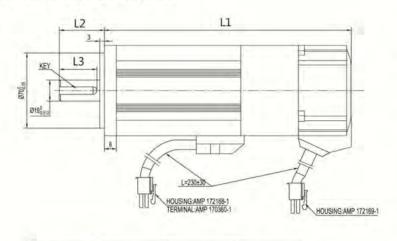
installation dimension

80 low voltage SERIES

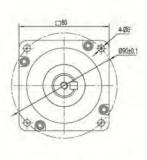
80 low voltage series(NO brake)

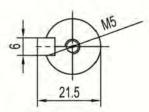


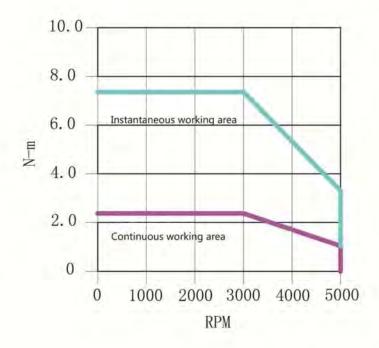
80 low voltage series (brake)



Model (80)	L1(MM)	L2(MM)	L3(MM)
750W	172±1	35±1	25









KSX5820

FRAMELESS SERIES SERVO MOTOR





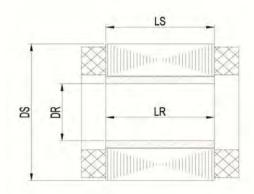
Model description

- For example:
- FSM : On behalf of the frameless servo motor
- 58: On behalf of the stator outside diameter 57.5
- 20: Represents stator height 20

Electrical Specifications

Model					
Power(W)	100	200	400	350	750
Stator Lam Dia(DS)	57.5	57.5	57.5	77	77
Length of stator core(LS)	10	20	40	30	45
Inner diameter of rotor core(DR)	24	24	24	32.65	32.65
Length of rotor core(LR)	10	20	40	30	45

Installation dimension





^{*}The above products are only representative products, and the derived products can be made according to customer requirements.





■ Features

- The stator epoxy is vacuum sealed, the heat dissipation and insulation performance are good, and the windings are effectively protected, which is suitable for all kinds of harsh environments.
- The stator adopts splicing structure, using excellent silicon steel material, super high slot full rate, reducing heating.
- The rotor is made of high-performance rare earth materials with extremely low cogging torque.
- Insulation grade H level
- Can be used for joint robot joint







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